1.Hall sensor

Hall current sensors are mainly used to isolate and convert AC, DC, pulse and other complex signals. After signacontrol of current signals are converted according to the Hall Effect Theory, they can be directly acquired by AD, DSP, PLC, secondary instruments and other devices. Hall current sensors are widely applicable for acquisition and feedback in the current monitoring, battery application, inverter, solar power management, direct current cabinet, DC motor drive, electroplating, welding, frequency converter, UPS servo control systems. They feature the quick response, wide range of measurement, high precision, strong overload capacity, good linearity and excellent anti-interference performance.

1.1 Open-loop Hall current sensor

1.1.1 Explanation for type



Technical parameters		1 .	Data				
1	ecnnic	al parameters	Split/closed open-loop	Hall (true RMS)			
		Nominal value	Voltage: ±5V/±4V	Current: 4-20mA			
Output	Zero offset voltage (current)		Voltage: ±20mV	Current: ±0.05mA			
Output	Offset voltage (current) drift		Voltage: ≤±1.0mV/°C	Current: ±0.04mA/°C			
		Linearity	≤0.2%FS				
Power voltage		ver voltage	DC±15V	DC 24V			
	Ba	indwidth	0-20kHz				
	Resp	ponse time	≤5us	≤1ms			
	Dielec	tric strength	Permissible 2500VAC between input/ output and power supply at the power frequency				
	Accu	aracy class	1.0				
Ambien	t	Temperature	Operating temperature: -25° C + 70° C; storage temperature: -40° C + 85° C				
conditior	18	Humidity	≤95%RH, no dew, no aggressive gas				
		Altitude	≤3500m				

1.1.2 Technical data

1.1.3 Split open-loop hall current sensor

1.1.3.1 Spec. and size (unit: mm)



Fig.1







Fig.2
115.2

Size	0	utline siz	ze	Tł	Through size			Mounting size	
Specification	W	Н	D	a	e	Φ	М	N	Figure
AHKC-EKA	60	64	16	/	/	20	47	/	Fig.1
AHKC-EKAA	60	64	16	/	/	20	47	/	Fig.1
AHKC-EKDA	60	64	16	/	/	20	47	/	Fig.1
AHKC-EKB	100	102	24	/	/	40	80	/	Fig.1
АНКС-ЕКВА	100	102	24	/	/	40	80	/	Fig.1
AHKC- EKBDA	100	102	24	/	/	40	80	/	Fig.1
АНКС-К	127	63	25	64	16	/	/	30	Fig.2
AHKC-KAA	127	63	25	64	16	/	/	30	Fig.2
AHKC-KDA	127	63	25	64	16	/	/	30	Fig.2
АНКС-Н	149	79	25	82	32	/	/	46	Fig.2
AHKC-KA	176	95.5	29	104	36	/	/	60	Fig.2
АНКС-НВ	204	111.5	29	132	52	/	/	$\frac{48}{2}$ ×	Fig.2

1.1.3.2 Cross-reference tables of spec. -parameter

Specification	Rated current	Power supply	Rated output	Measuring aperture (mm)	Precision degree
AHKC-EKA	0∼(20-500)A	±15V	5V	φ 20	1
AHKC- EKAA	DC 0~(50-500)A	12V/24V	4~20mA	φ 20	1
AHKC- EKDA	AC 0~(50-500)A	12V/24V	4~20mA	φ 20	1
AHKC-EKB	0~(200-1000)A	±15V	5V	φ40	1
AHKC- EKBA	DC 0~(200- 1000)A	12V/24V	4~20mA	φ40	1

	AHKC- EKBDA	AC 0~(200~ 1000)A	12V/24V	4~20mA	φ40	1
	AHKC-K	0~(400-2000)A	±15V	5V	64×16	1
	AHKC- KAA	DC 0~(400- 2000)A	12V/24V	4~20mA	64×16	1
	AHKC- KDA	AC 0~(400- 2000)A	12V/24V	4~20mA	64×16	1
1	АНКС-Н	0~(500-3000)A	±15V	5V	82×32	1
3	АНКС-КА	0~(500-5000)A	$\pm 15V$	5V	104×36	1
	AHKC-HB	0~(2000-20000)A	±15V	5V	132×52	1

Note: Rated current unlabeled indicates that AC and DC input current can be measured, please specify when ordering.

1.1.4 Closed hall current sensor







Fig.1





Fig.2

Size	Outline size(mm)			Through size(mm)			Mounting size(mm)		Figure
Specification	W	Н	D	a	e	Φ	М	Ν	0
АНКС-Е	53	72	16	/	/	21	47	/	Fig.1
AHKC-LT	90	73.5	25	/	/	32.5	74.5	71	Fig.1
AHKC-BS	43	32.5	19	20.5	10.5	/	/	/	Fig.2
AHKC-BSA	43	32.5	19	20.5	10.5	/	/	/	Fig.2
AHKC-F	74	57	22	43	13	/	/	22	Fig.2
AHKC-FA	94	60.5	26.5	52	15	/	83	28	Fig.2
AHKC-HAT	94	76.5	24	52.5	32	/	83	28	Fig.2

1.1.4.2 Cross-reference tables of spec. -parameter



	Specification	Rated current	Power supply	Rated output	Measuring aperture (mm)	Precisio n degree
	AHKC-E	0~(20-500)A	±15V	5V	φ 20	1
	AHKC-LT	0~(100-800)A	±15V	5V	φ 32.5	1
	AHKC-BS	0~(20-500)A	±15V	5V	20.5*10.5	1
V	AHKC-BSA	DC 0~(50-500)A	12V/15V/24 V	4~20mA	20.5*10.5	1
- PI	AHKC-F	0~(200-1000)A	±15V	5V	43*13	1
	AHKC-FA	0~(200-1500)A	±15V	5V	52*15	1
1	AHKC-HAT	0~(400-2000)A	±15V	5V	52*32	1

Note: Rated current unlabeled indicates that AC and DC input current can be measured, please specify when ordering.

1.1.5 Wiring Method

1.1.5.1 Split/closed open-loop hall current sensor

Definition of wiring terminals •





1.1.5.2 Hall current sensor (true RMS)

• Definition of wiring terminals



2 Closed-loop Hall current sensor

Closed-loop Hall current sensor is also called Hall magnetic balancing current sensor. It incorporates the mentioned theory with magnetic balancing theory. In other words, the ferromagnetic field concentrator concentrates the magnetic field generated by primary current and applies it to the Hall component. Then the voltage signal output from Hall component is amplified and becomes the input of power amplifier. The offset current output flows through the secondary compensating coil. The magnetic field generated by primary current. In such way, the primary field is compensated and the Hall output is reduced gradually. When the primary field is equivalent to the secondary one and the offset current keeps stable, it is the magnetic balancing. This circuit mainly consists of electromagnetism conversion component, circuit amplifier and drive compensating circuit.

2.1 Explanation for type



2.2 Spec. and size (unit: mm)

2.2.1 Outline size of AHBC-LTA



2.2.2 Outline size of AHBC-LT1005







2.2.3 Outline size of AHBC-LF







2.3 Cross-reference tables of spec. -parameter

Specification	Rated current	Power supply	Rated output	Measuring aperture (mm)	Precision degree
AHBC-LTA	100~300A	±15V	50mA /100mA	φ 20	0.5
AHBC- LT1005	1000A	±15V	200mA	/	0.5
AHBC-LF	2000A	±15V	400mA	/	0.5

Note: AC and DC input current can be measured, please specify when ordering.

2.4 Wiring method

• Definition of wiring terminals



Note: 1. Analog output GND must be connected with Power Ground.

2. Please select the correct current flow direction.

2.5 DC leakage current sensor

DC leakage current sensor is a measuring module that converts the measured direct current into the proportional direct current or voltage signal according to the flux gate theory and the input side is highly insulated from the output side. Typical outputs include 4-20mA, DC0-5V and DC0-10V signals. These standard signals can be acquired by various devices such as PLC, RTU and DAS card and used for different current monitoring applications. leakage current transformerS surround the outlet + and – of DC circuit. It detects output signals of sensors in circuit branches. If the insulation in circuit branches is normal, the current passing the sensor must be equal in the opposite direction. The output signal is zero. If a circuit branch is grounded, the differential current passes the leakage current transformer and the output of sensor is not zero.Therefore, it is possible to identify the grounded branch in the DC system by detecting output signals from circuit branches.The theory guarantees the accurate line identification and prevents the influence of distributed capacitance.

2.5.1 Explanation for type







Fig.1

Fig.2



Size	(Outline s	size(mm)	Through size(mm)	Mou size(nting (mm)	Figure
specification	W	Н	D	Φ2	Φ1	М	Ν	8
AHLC-LTA	68	57	20	50	20	52	52	Fig.1
AHLC-EA	100	108	30	75	40	78	/	Fig.2
AHLC-EB	120	112	30	94	60	98	/	Fig.3

2.5.3 Cross-reference tables of spec. -parameter

Specification	Rated current	Power supply	Rated output	Measuring aperture (mm)	Precision degree
AHLC-LTA	DC 10mA~2A	±15V	5V	φ 20	1
AHLC-EA	DC 10mA~2A	±15V	5V	φ40	1
AHLC-EB	DC 10mA~2A	±15V	5V	φ 60	1

2.5.4 Wiring method

Definition of wiring terminals



2.6 DC voltage sensor

ACTDS series DC voltage sensors are the measuring module that converts the measured DC voltage into the proportional DC current or DC voltage signal according to the optical isolation theory. The input side is highly insulated from the output side. They feature the high accuracy, linearity and integration, small size, simple structure, long-term stability and adaptability to various working conditions. They are widely used for system control and detection of electrical equipment in the power, petroleum, mine, chemical, railway, communication, building automation sectors. <0}

- \star Measurement of DC voltage
- ★ Quick response
- \star Large overload capacity
- \star High accuracy
- \star DIN rail mounting
- \star 3.5kV insulation between the input side and the output side

2.6.1 Explanation for type



Acrel DC voltage sensor

Customized power supply: DC12V, DC15V, DC24V or DC48V

2.6.2 Technical data

Technical	parameters	Index			
Incont		Rated voltage DC300~1500V			
Input		Measuring voltage range 120% * Vpn			
Nominal valueOutputOverload protectionLoad resistance		voltage: DC 0-5V、DC0-10V; current: DC 4-20mA、DC 0-20mA			
		Max. output≤ 150% of full scale			
		$>5000\Omega(voltage output)/<450\Omega(current output)$			
Power supply		DC12V / DC15V / DC24V / DC48V (Optional)			
Precision degree		0.5			
withstand voltag	e	Power frequency withstans voltage 3500VAC between input/ output and power supply			
Linearity error		0.2%			
Offset voltage $(Ta = +25^{\circ}C)$	/ Offset Current	50 mV (correspond to the voltage output)/80 uA (correspond to the current output)			
Response time		\leq 30mS			
Insulation resista	ance	$>20M\Omega@DC500V$			
Installation method		With guide rail TS35			
Temperatur		Operating temperature:-10°C-+55°C;			
Ambient		storage temperature: -40°C-+85°C			
conditions	Humidity	≤93%RH, no dew, no aggressive gas			
	Altitude	≤2500m			

2.6.3 Spec. and size (unit: mm)





2.6 .4wiring method





power supply

output

input

Terminal	1	2	5	6	3	4
Idetificatio n	power+	Power GND (G)	output-	output+	input -	input -

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